

# Development and test of a low-cost ground terminal for ~~ACES-MWL~~

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## Outline

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### **Objective 1: Make at least 1 G/T operational**

- Revival of the old Computer Infrastructure
- Re-Evaluate Earlier Measurements
- Activities with the G/T RF EGSE
- Improved T&F Infrastructure
  - Short- and long-term performance

### **Objective 2: Modernise G/T hardware**

- 2-way: Current state-of-the-art, where to go?
- Cost Reduction...
  - Digital Implementation, SATRE TWSTFT
  - Breadboarding

## **Outlook**

# Revival of the old Computer Infrastructure, VMware

EM-Server

- 📁 DataCollector-ACES-7.19 use for EM\_migrated
- 📁 DataRecorder-ACES-21-4 use for EM\_migrated
- 📁 Free\_MWL\_EM\_123.99 use for EM\_migrated
- 📁 SLES11.1-64-ACES-2 GT-42
- 📁 X2-VM-123.73 ACES GT-3 controller use for EM\_migrated
- 📁 X2-VM-123.93 GT-2 Controller use for EM\_migrated
- 📁 X2-VM-73clone ACES GT Controller-2
- 📁 X3-VM-74-i3 ACES EM use for EM\_migrated
- 📁 X4-VM-75 MWL EGSE controller use for EM\_migrated
- 📁 X5-VM76-i3 EGSE Controller use for EM\_migrated

FM Blue Box

- 📁 FS-DataCollector-ACES-19\_restored
- 📁 FS-FeeNAS-99\_restored
- 📁 FS-SLES12SP2-DR-MWL-21
- 📁 SLES11.1-64-ACES-1 FS-43
- 📁 X3-FS-Analyser-74\_restored
- 📁 X3-VM-74clone-FS
- 📁 X4-FS-Power control-75\_restored
- 📁 X4-VM-75clone-FS (do not use, use EM instead)
- 📁 X5-FS-RF-EGSE Control-76 allways off\_restored

Veeam-Server: 22-10-19 14:25:46

FM Blue Box **Veeam-Server: 22-10-19 14:24:23**

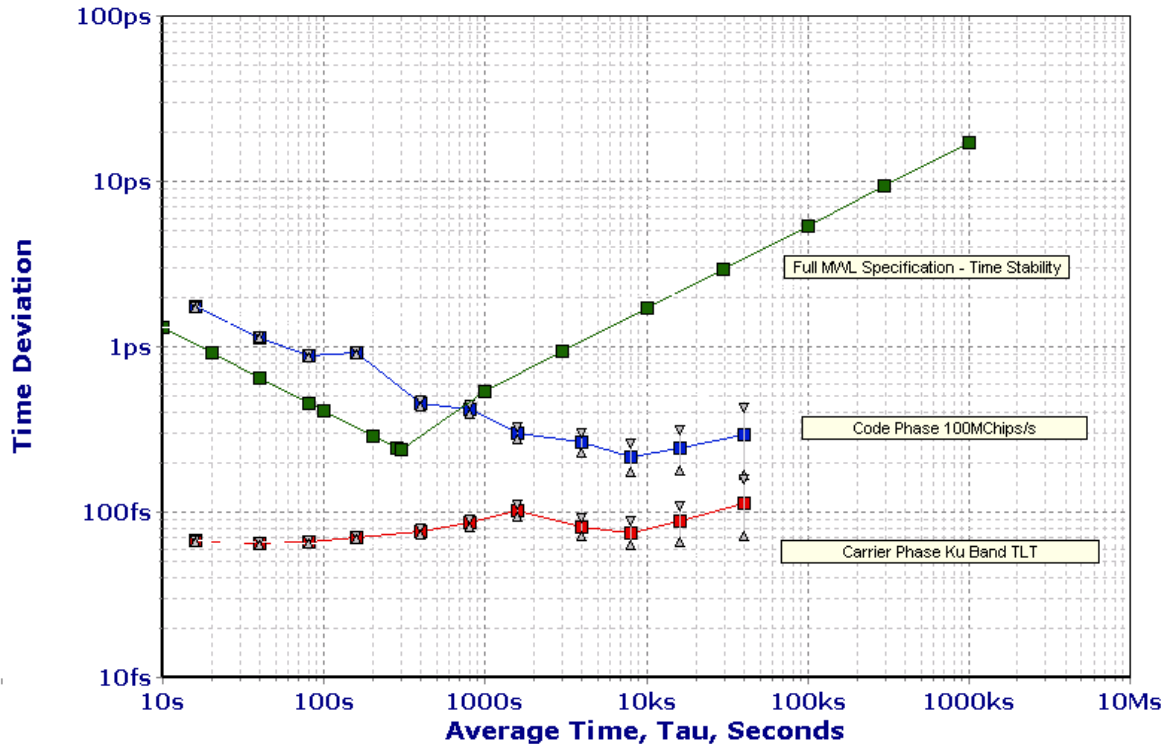
**EM Server:** 10 virtual machines running, incl G/T controller

**FM Blue Box** (part of EGSE)  
8 virtual machines running

The full set of M&C computers has been restored from backup, is again available in virtualised environment (VMware)

# Re-Evaluate Earlier Measurements (read from database)

top: Code Phase, bottom: Carrier Phase



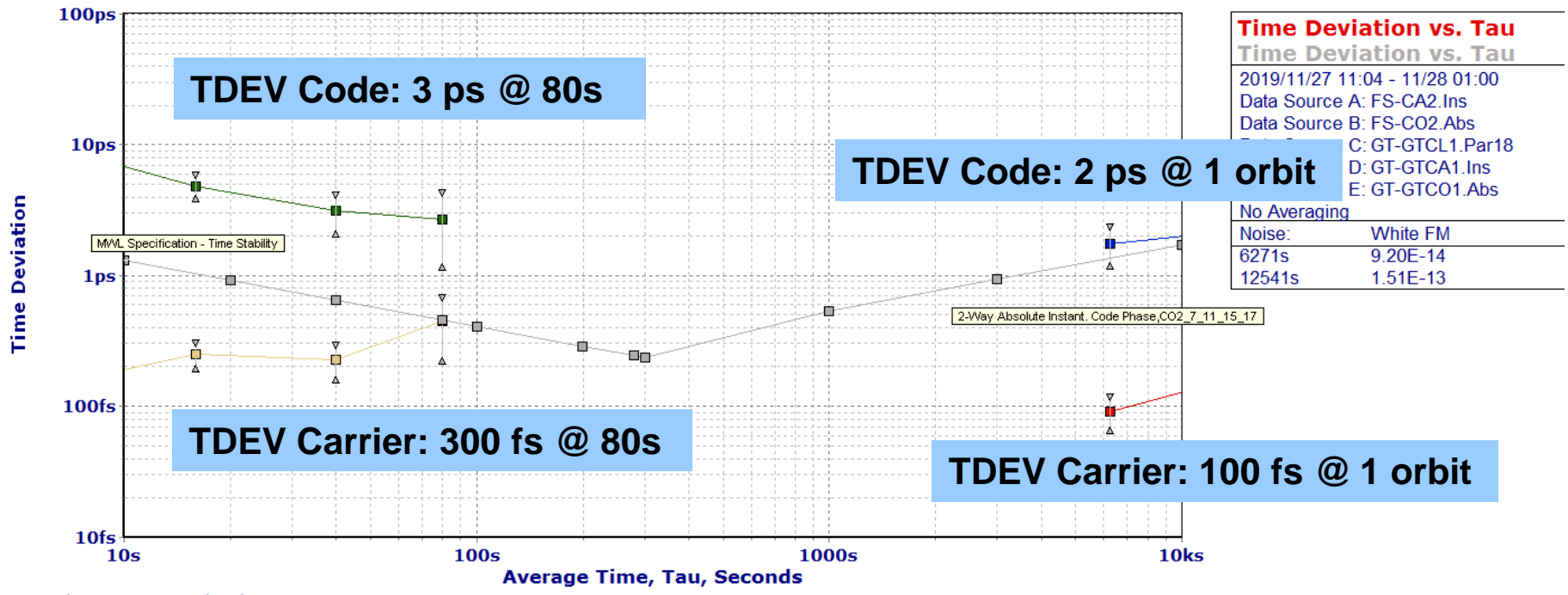
DataAnalyzer v3.4 © TimeTech GmbH 2011

Time Deviation vs. Tau	
Time Deviation vs. Tau	
2019/01/18 19:00 - 01/21 11:59	
Data Source A: GT-GTCA1.Ins	
Data Source B: GT-GTC01.Abs	
No Averaging	
Noise:	White PM
2s	1.39E-13
4s	9.53E-14
8s	7.67E-14
16s	6.69E-14
40s	6.45E-14
80s	6.59E-14
160s	7.00E-14
400s	7.71E-14
800s	8.60E-14
1600s	1.03E-13
4000s	8.21E-14
8000s	7.52E-14
16000s	8.79E-14
40000s	1.14E-13

## G/T with continuous Test-Loop Translator, carrier phase stays at 100 fs for 3 days

Database and data-analysis fully functional

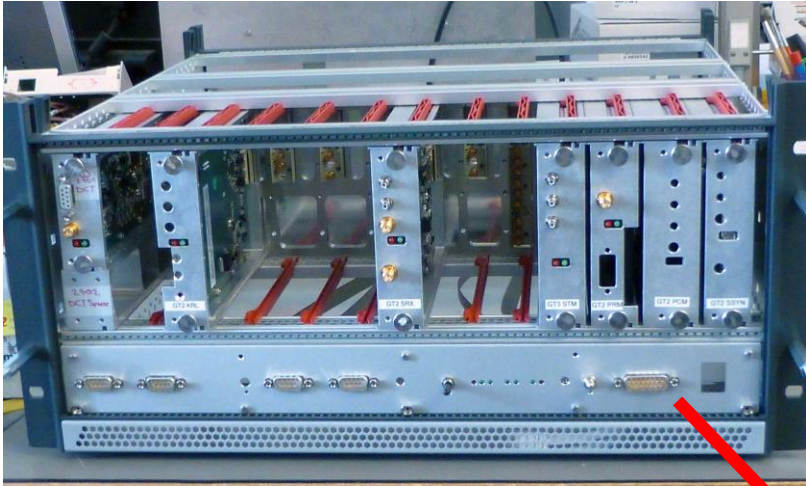
# Re-Evaluate Earlier Measurements (2), End-to-End Test



- Lambda config, FS & G/T with realistic orbits, incl. Doppler
- Right data: 1 point / orbit
- Reproducible, estimate carrier cycle / orbit
- TDEV carrier phase: 100 fs in the long run



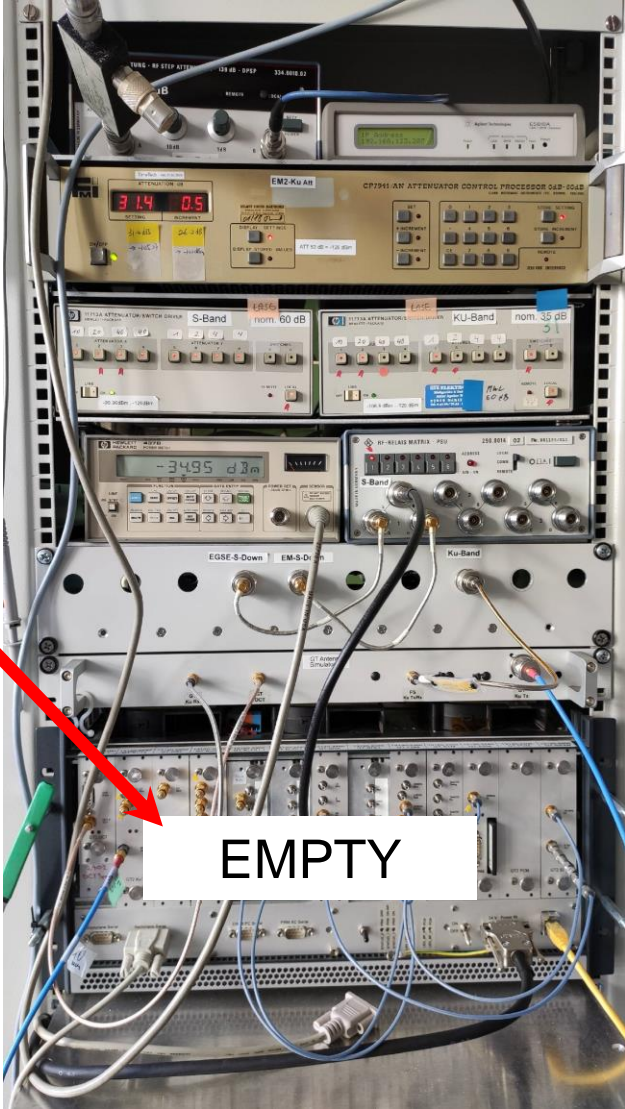
# Activities with the G/T RF EGSE: ready to accept test items



The right picture is from my last presentation 2019, holding GT #2

Today, the G/T drawer (above) is mostly empty, awaiting modules to be tested.

Otherwise, the G/T RF EGSE is unchanged



EM S-Band level

EM Ku-Band level

EGSE level S&Ku

GT vs EGSE S-selection

Ku-RF combiner  
Antenna simulator  
Test-Loop

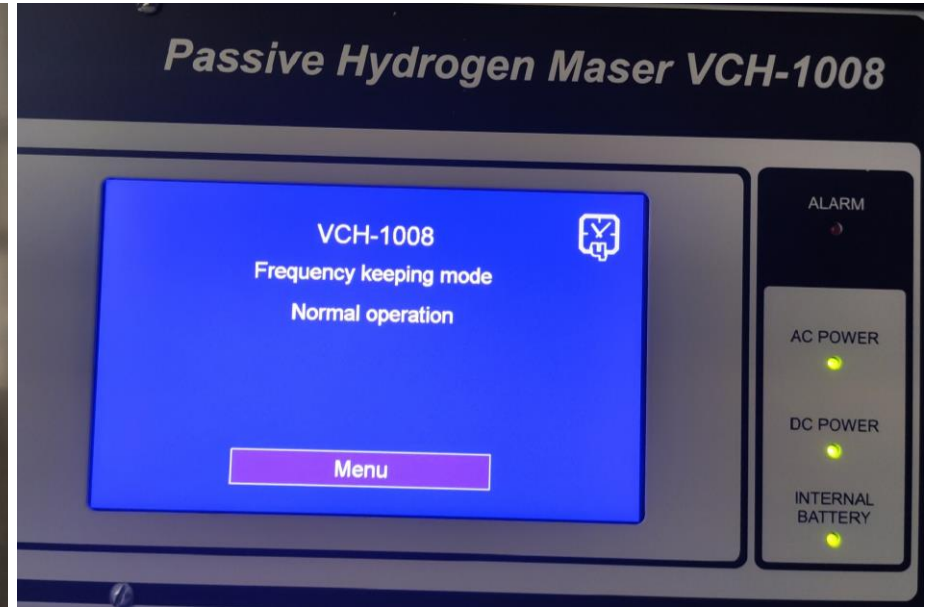
GT #2, fully assembled

EMPTY

# Improved T&F Infrastructure, Hardware



Operational 2-way link using SATRE Modem



RAKON USO:  $4E-14@ 1s$ , locked to PHM Steered to UTC(PTB) via 2-way, time constant 1 day

# Improved T&F Infrastructure, 100 MHz Phase Noise



PN of 100 MHz signal approx 10 dB better than best Swiss Maser  
 Test equipment: R&S FSWP



# Improved T&F Infrastructure, Phase Measurements

Modified Allan Deviation (Mod  $\sigma_y(\tau)$ )



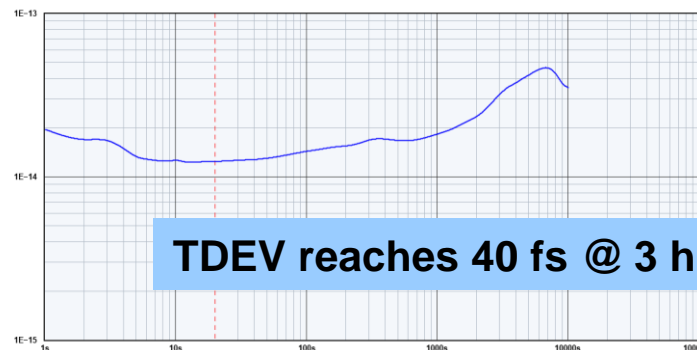
Tau	Sigma(Tau)
1s	3.40E-14
2s	1.47E-14
4s	6.46E-15
8s	2.72E-15
10s	2.20E-15
20s	1.08E-15
40s	5.56E-16
80s	3.02E-16
100s	2.50E-16
200s	1.35E-16
400s	7.42E-17
800s	3.78E-17
1000s	3.19E-17
2000s	2.05E-17
4000s	1.65E-17
8000s	9.31E-18
10000s	6.15E-18

**MDEV reaches 1E-17 @ 3 hrs**

Trace	Notes	DUT Freq	MDEV at 20s	RMS Jitter (1 Hz-100 kHz)	Duration	Acquired	Time/Date
AHMPLL 3.6, #1 vs #3, 2'47k, with ground (Unsaved)	REF TIM 5 MHz, Pin 9.6 dBm, unit vs unit	100.0 MHz	1.08E-15	2.7E-14 s	15 h	51848 pts	18.10.2022 19:15:23

**Comparison between two 100 MHz generators 15 hrs**

Time Deviation  $\sigma_x(t)$

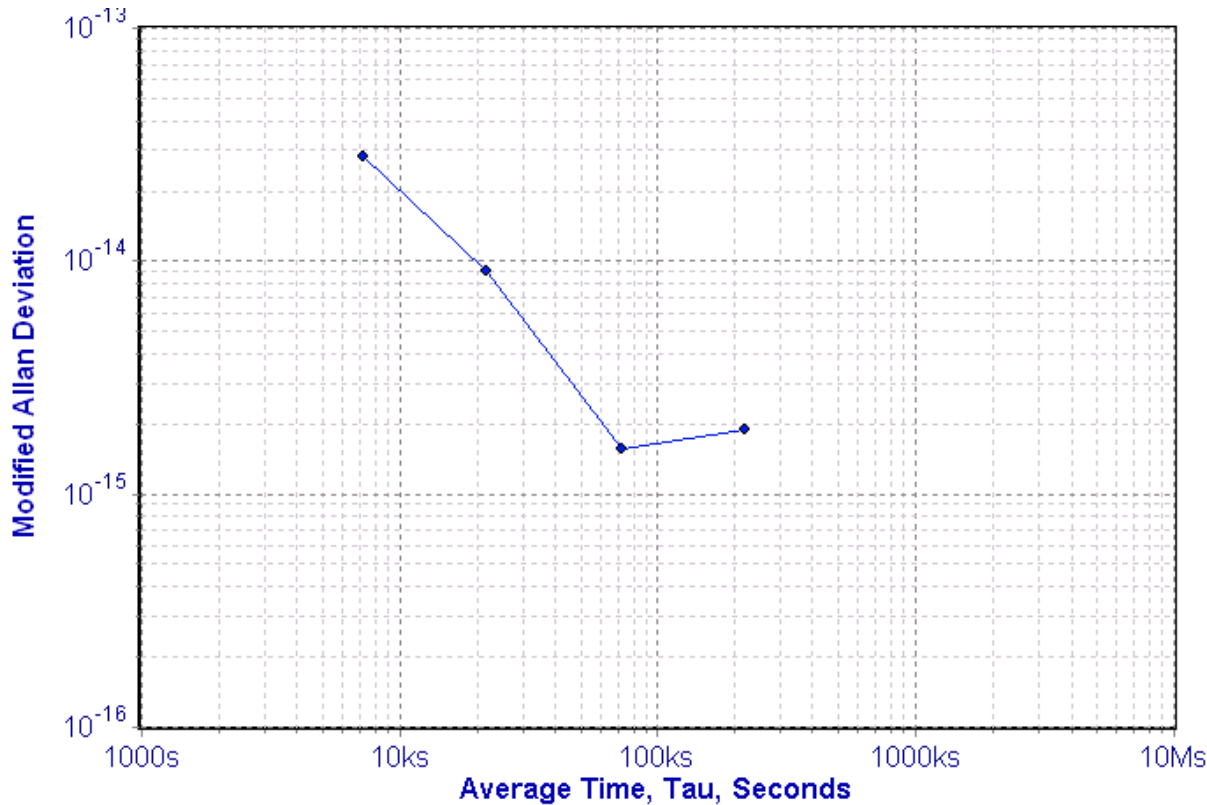


Tau	Sigma(Tau)
1s	1.86E-14
2s	1.70E-14
4s	1.49E-14
8s	1.28E-14
10s	1.27E-14
20s	1.25E-14
40s	1.28E-14
80s	1.40E-14
100s	1.44E-14
200s	1.58E-14
400s	1.71E-14
800s	1.75E-14
1000s	1.84E-14
2000s	2.35E-14
4000s	3.81E-14
8000s	4.49E-14
10000s	3.52E-14

**TDEV reaches 40 fs @ 3 hrs**

Trace	Notes	DUT Freq	TDEV at 20s	RMS Jitter (1 Hz-100 kHz)	Duration	Acquired	Time/Date
AHMPLL 3.6, #1 vs #3, 2'47k, with ground (Unsaved)	REF TIM 5 MHz, Pin 9.6 dBm, unit vs unit	100.0 MHz	1.25E-14	2.7E-14 s	15 h	51779 pts	18.10.2022 19:15:23

# T&F Infrastructure, PHM long-term performance



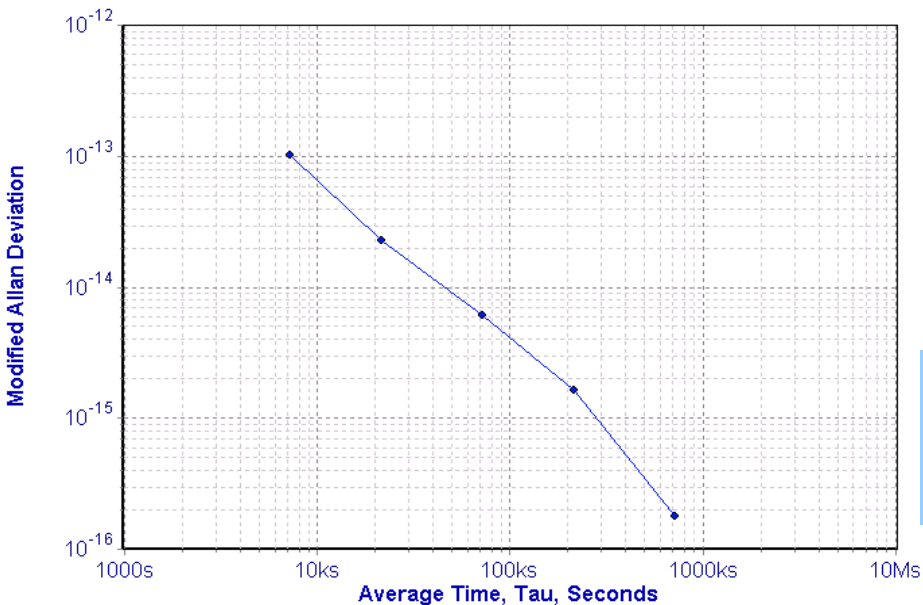
Modified Allan Deviation vs. Tau	
Start Time:	2022/03/01 00:04
End Time:	2022/03/31 22:04
Span:	30 days 22 hours
Noise:	Flicker PM
7200s	2.77E-14
21600s	9.08E-15
72000s	1.57E-15
216000s	1.89E-15

Tester: 22-10-17 15:26:31

Free-running PHM VCH-1008, compared to UTC(PTB), March 2022  
 Approx 1.5E-15 @ 1 day

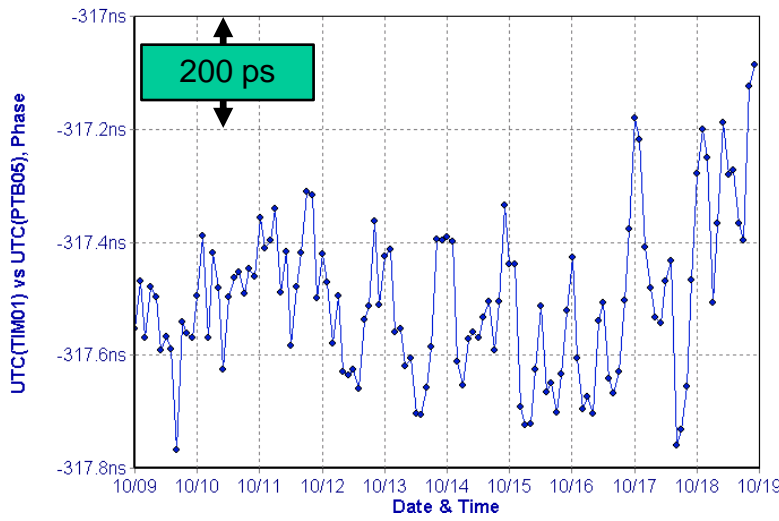


# T&F Infrastructure, PHM locked to UTC(PTB), time constant 1 day, in-loop performance, ITU-files



Modified Allan Deviation vs. Tau	
Start Time:	2022/08/16 00:04
End Time:	2022/10/18 22:04
Span:	63 days 22 hours
Noise:	White PM
7200s	1.02E-13
21600s	2.27E-14
72000s	6.12E-15
216000s	1.62E-15
720000s	1.78E-16

**MDEV 1.8E-16 @ 8 days during 64 days In-loop**

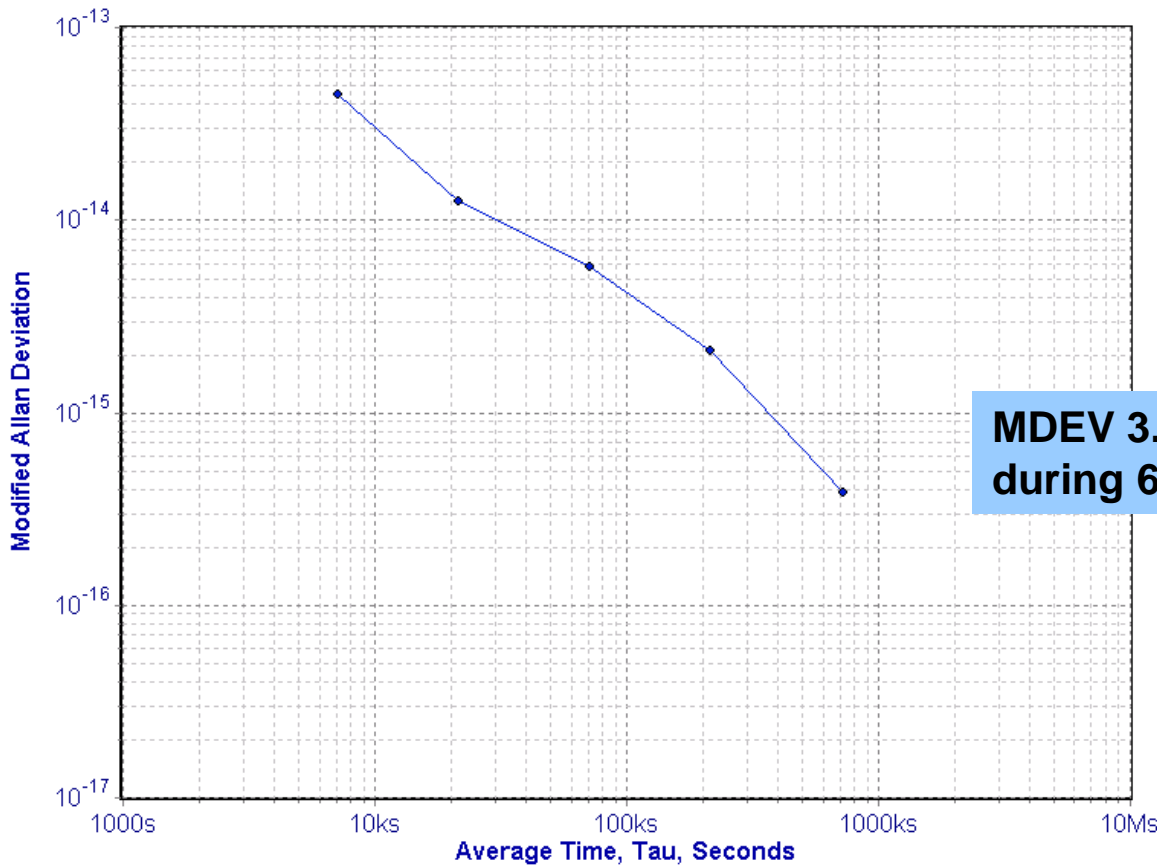


UTC(TIM01) vs UTC(PTB05)	
Start Time:	2022/10/09 00:04
End Time:	2022/10/18 22:04
Span:	9 days 22 hours
Sample Interval:	7200 s
Min:	-317768.500 ps
Max:	-317086.000 ps
Mean:	-317502.992 ps
PP:	682.500 ps
DRMS:	129.421 ps
Std.Dev:	138.809 ps
Drift / Second:	1.011E-16
Scale:	200 ps/div
Normalized by:	none

**StDEV 140 ps during 10 days**

WS: 22-10-19 22:58:08

# T&F Infrastructure, PHM locked to UTC(PTB), compared to Sweden (SP), using ITU-files



Modified Allan Deviation vs. Tau	
Start Time:	2022/08/16 00:37
End Time:	2022/10/19 18:37
Span:	64 days 18 hours
Noise:	Flicker PM
7200s	4.48E-14
21600s	1.25E-14
72000s	5.64E-15
216000s	2.09E-15
720000s	3.81E-16

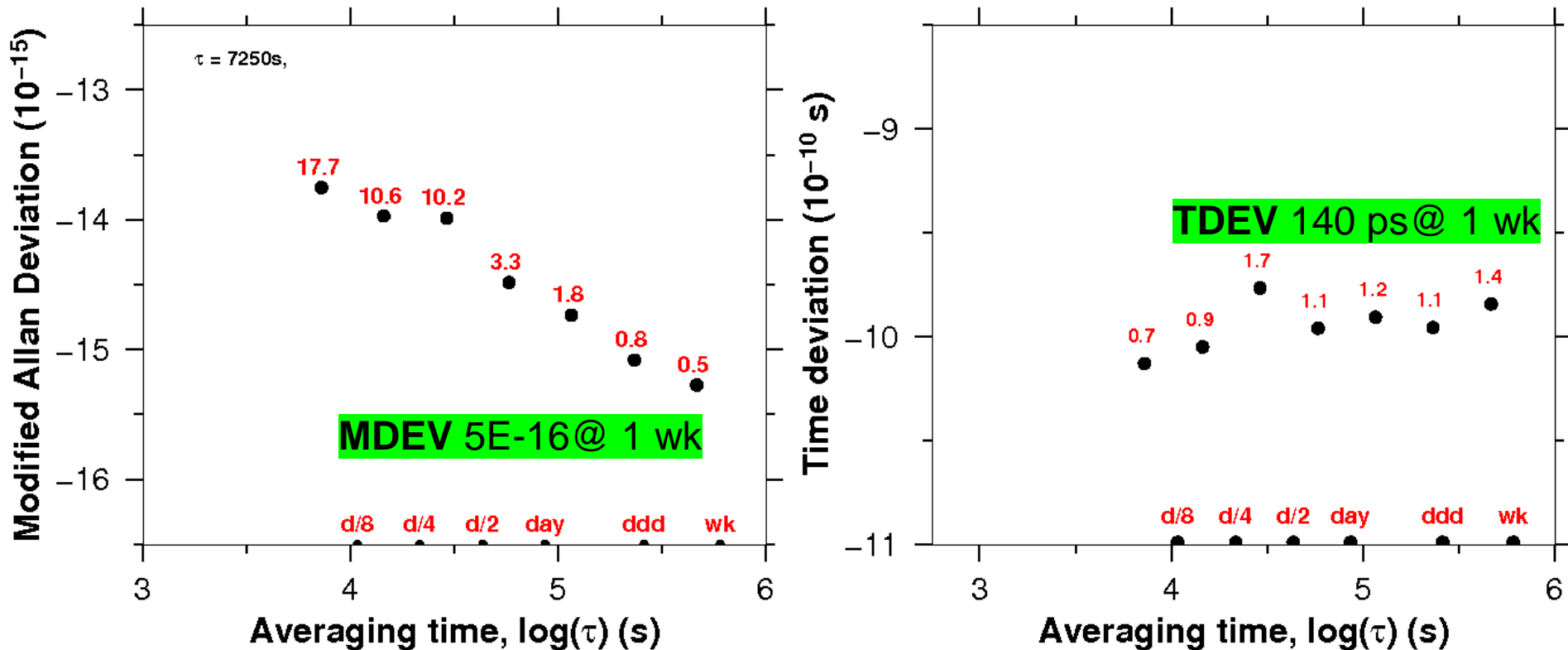
**MDEV 3.8E-16 @ 8 days during 64 days**

**SP: 3.8E-16 @ 8 days**  
**NIST: 1E-15 @ 8 days**  
**USNO: 3E-16 @ 8 day**

**Proof: compare to other, independent time scales**

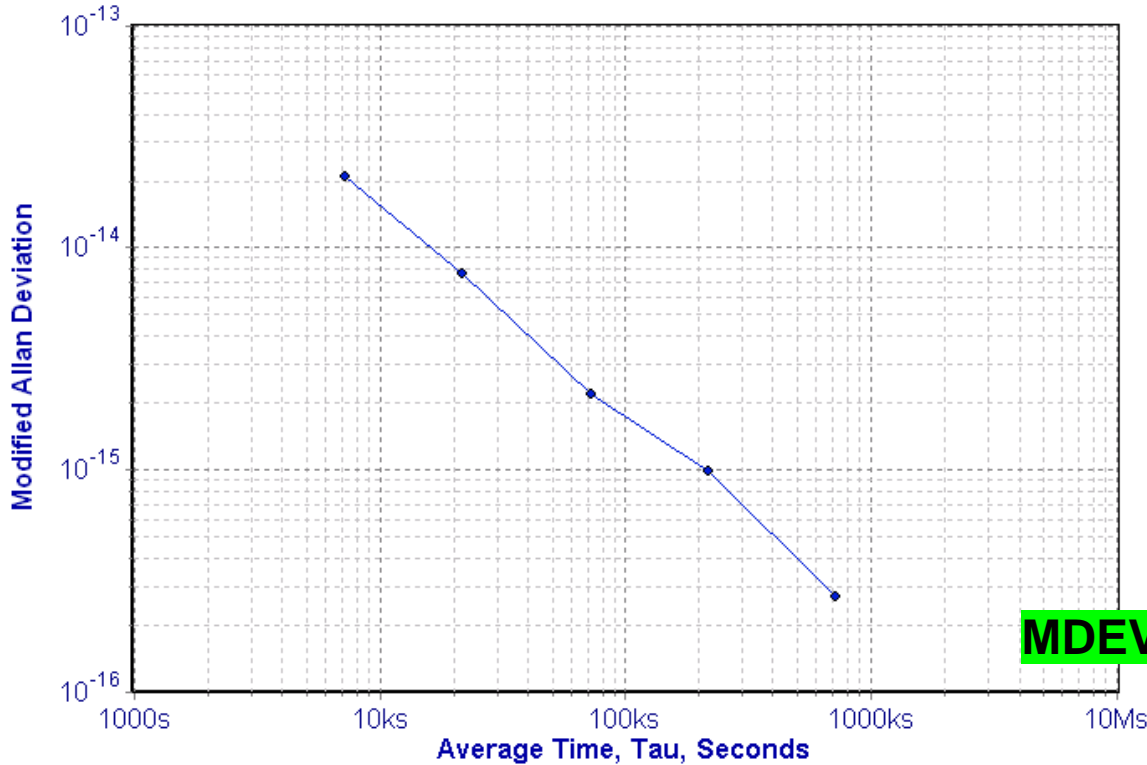
## 2-way: Current state-of-the-art: where to go?

From the BIPM web server: PTB vs USNO (best Ua 200 ps)



[https://webtai.bipm.org/ftp/pub/tai/timelinks/lkc/2207/usnoptb/lnc/usnoptb.t3b3\\_.gif](https://webtai.bipm.org/ftp/pub/tai/timelinks/lkc/2207/usnoptb/lnc/usnoptb.t3b3_.gif)

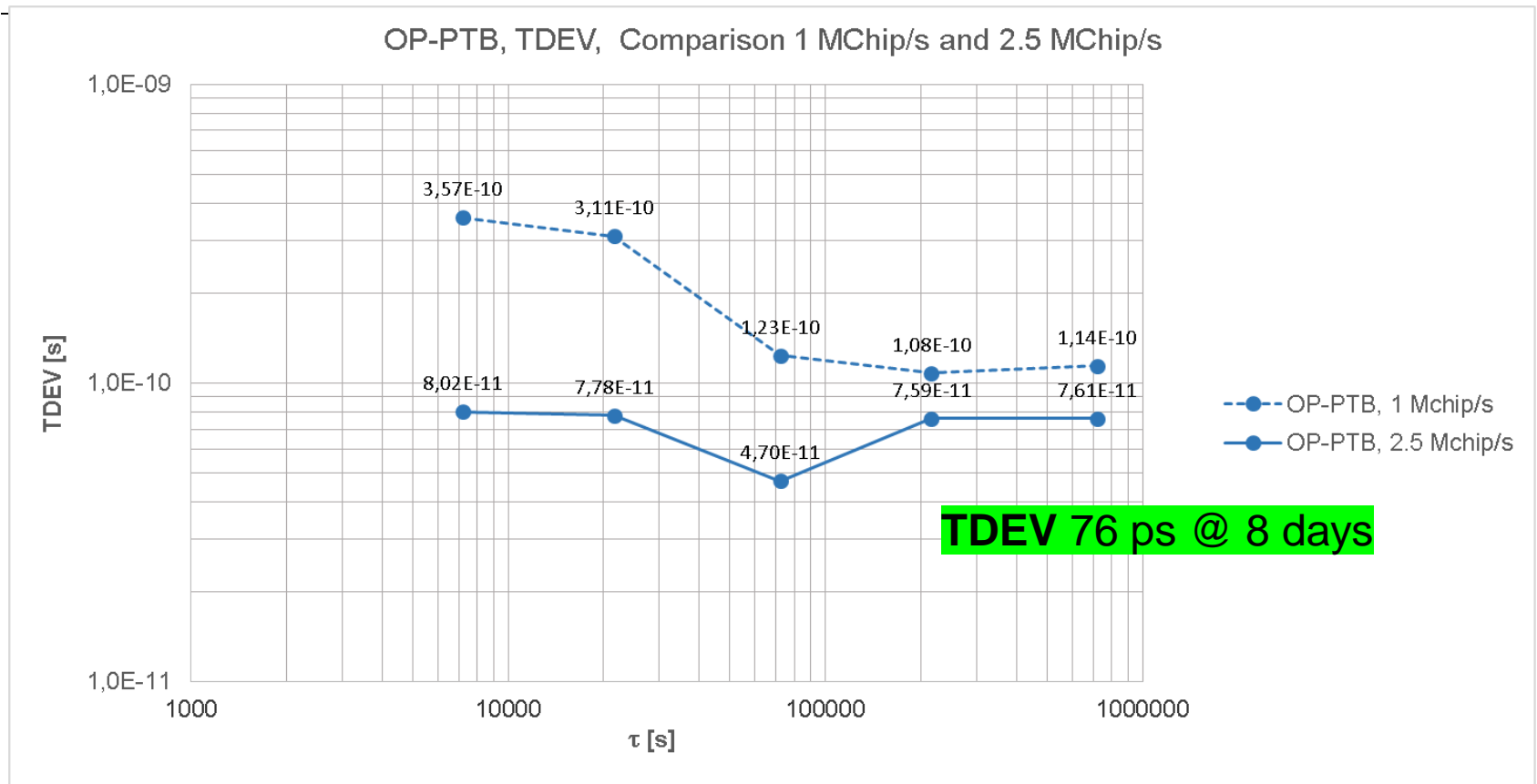
# USNO – PTB, 2022, 2.5 MChip/s, duration: 54 days



Modified Allan Deviation vs. Tau	
Start Time:	2022/08/26 00:46
End Time:	2022/10/18 22:46
Span:	53 days 22 hours
Noise:	Flicker PM
7200s	2.08E-14
21600s	7.65E-15
72000s	2.19E-15
216000s	9.82E-16
720000s	2.66E-16

**MDEV 2.7E-16 @ 8 days**

# OP - PTB, 2021-2022, 1 MChip/s vs 2.5 MChip/s, 54 days



Expected improvement by increasing the chip rate, 1 .. 2.5 MChip/s

Current systems fall short in the view of science and clock developments, like ACES: 1E-17 and far away from 1E-18 goals, which are around

# Cost Reduction: Digital Implementation



**Zynq 7020: 125 MSa/s,  
SATRE: 20 MCh/s and higher**

Digital implementation of SATRE  
Full set of features, ongoing



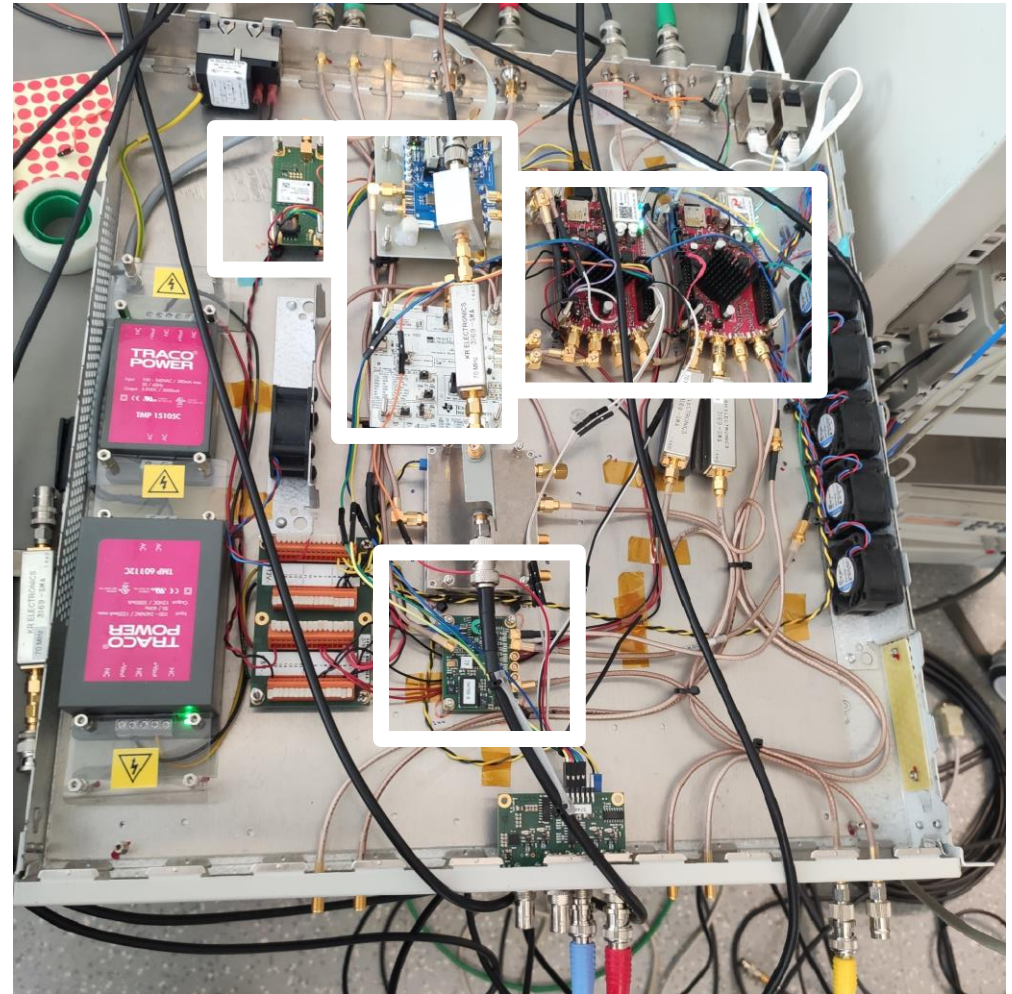
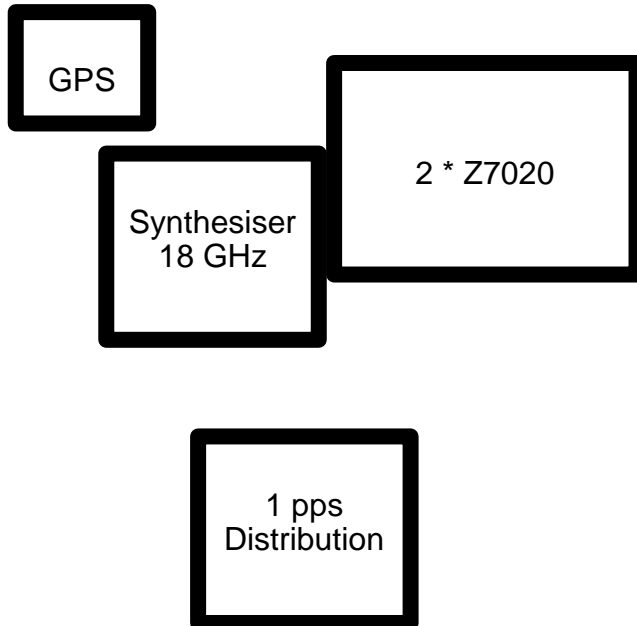
**Red Pitaya 250MSa/s,  
1 pps input**

**Compatible with MWL signal  
structure, code and carrier**

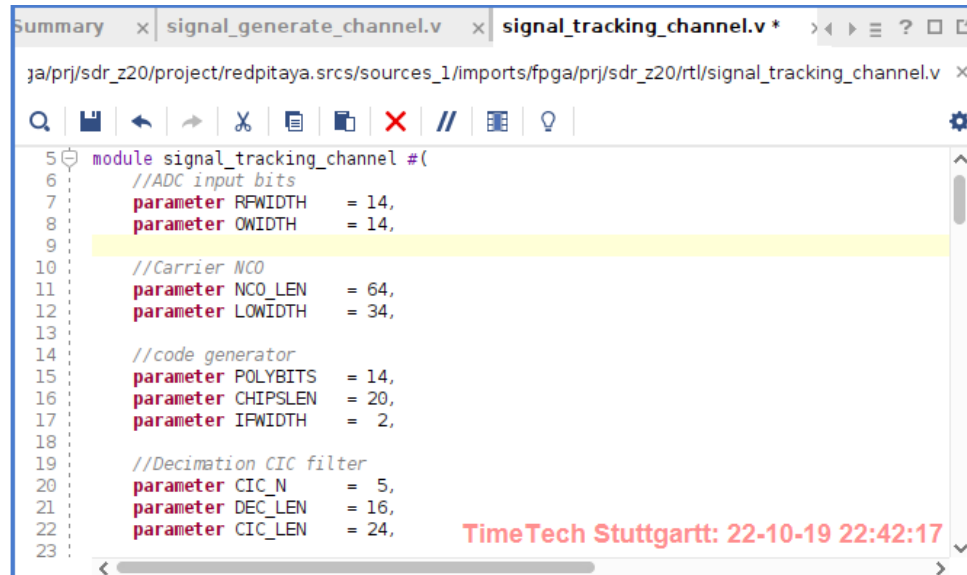
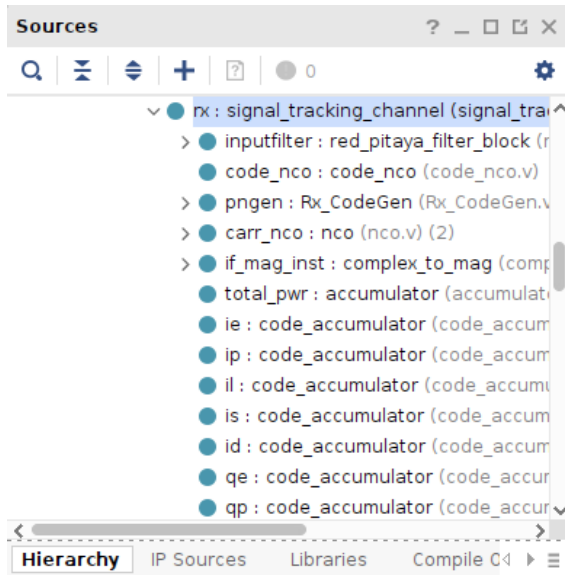
**Activity started**



# Breadboarding: Digital SATRE: Tx and Rx, direct sampling receiver

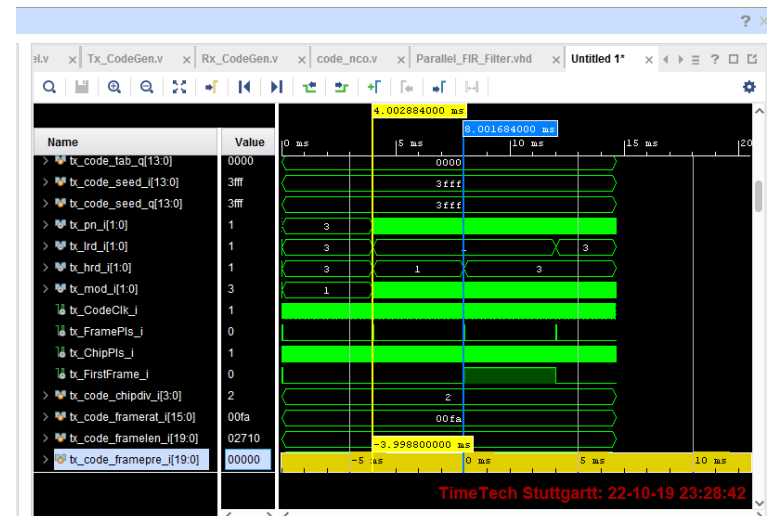


# Breadboarding: Development Chain

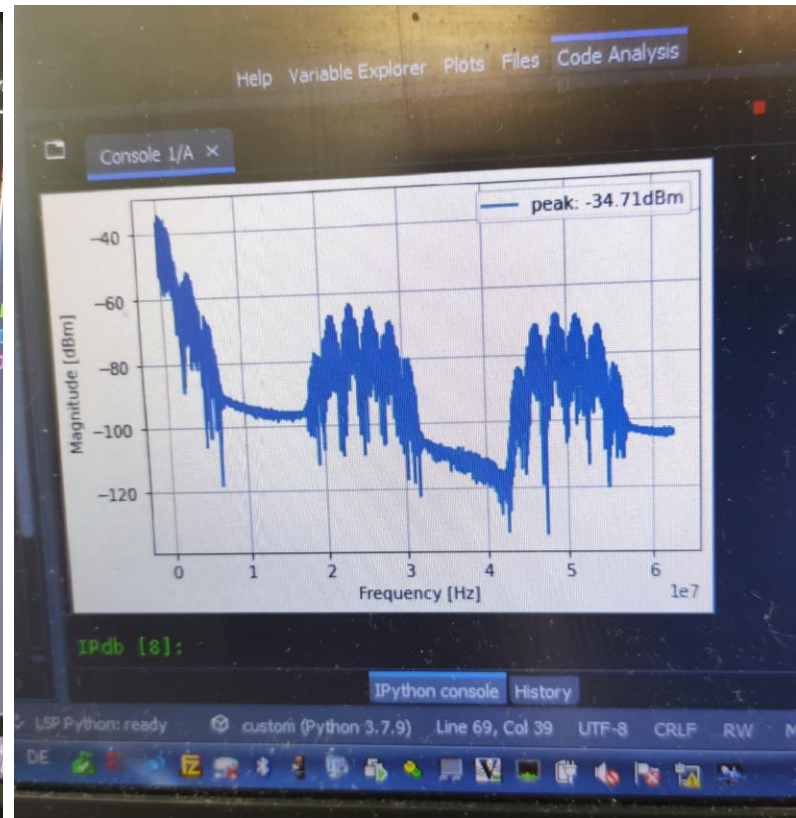


Development Chain, incl.

- All-VHDL implementation
- No copyrighted libraries
- Bitwise Simulation



# Beardboarding: Development and Verification



## Digital Signal Analysis Internal Test Points, DAC output to Scope

- 1 pps
- PN Sequency
- Modulated RF

## Numerical Signal analysis, incl FFT

Zero IF, showing data modulation

## SDR Major elements and progress

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- Major elements realised in FPGA
  - > **40x FPGA cores** developed / verified by test bench incl.
    - different DDS approaches, look-up table & CORDIC, PID controller, modulation, demodulation, saturation, complex multiplier, decimator etc.
- **Major C code elements** incl. FPGA DDR interface, data streaming, FFT etc, running on embedded ARM cores in ZYNQ SoC
- **Code re-use from SATRE**, but compiled in high level language

## Conclusion: „Low-Cost MWL“ ground terminal

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- Low-cost MWL G/T is not commercially feasible, reproduction of G/T impossible due to obsolescence
- Chip-shortage prohibits any fast solution
- „Market research“: Investment **too high** for a short mission like ACES
- ACES MWL: Lets optimise, what is available
- Maximise operational outputs

## Conclusion, Outlook signal reception

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- Aim for highest possible chip rates
- Direct Sampling is complex for BW above few 100 MHz, although this is definitely the future
- Allows for multi-channel operation
- But: Not ready „now“
  
- **MWL-Rx mixed signal architecture** can be scaled to 1 GSa/s and above, ground and space, But single channel reception only
  
- **In the near term, ACES-MWL architecture is most promising**

## Conclusion, Outlook: Satellite and transponder selection

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- Traditional bent-pipe transponders have limited capabilities, even at very high BW (500 MHz and up)
- Better use on-board signal regeneration, multiple channel operation, all links like ACES-MWL
- Downlink the translation oscillator as separate signal
- Transmit coherent carrier and modulation, cycle identification
- 32, 48 GHz and up

**Plan for dedicated, optimised transponder(s)  
in GEO orbit, optimise footprint**